

Robotics Engineering

Hard · 16 × 16 · 18 words · every direction, backwards too

E	E	P	O	O	L	K	C	A	B	D	E	E	F	G	L
N	S	O	S	C	I	T	A	M	E	N	I	K	N	A	R
S	R	D	O	O	O	F	A	T	A	R	M	I	P	E	R
A	O	O	T	R	W	T	A	H	E	H	N	I	L	C	O
C	T	M	T	E	T	O	D	D	A	N	D	L	I	P	T
C	A	E	M	H	T	E	O	P	A	C	O	I	A	E	O
E	L	T	A	A	O	C	T	L	O	R	I	Y	A	U	M
L	U	R	N	E	N	I	P	N	T	E	L	R	E	Q	O
E	P	Y	T	E	C	H	T	N	P	O	E	A	O	R	V
R	I	E	T	N	T	R	O	O	A	N	I	I	I	O	R
O	N	A	B	A	O	C	C	D	H	F	O	O	N	T	E
M	A	T	P	L	O	S	R	A	D	I	L	G	M	B	S
E	M	T	L	R	O	T	O	M	R	E	P	P	E	T	S
T	N	E	C	R	S	N	F	H	M	E	E	A	N	I	R
E	R	I	Y	T	R	A	J	E	C	T	O	R	Y	I	E
R	M	G	L	M	R	O	T	C	E	F	F	E	D	N	E

- ☐ KINEMATICS
- ☐ END EFFECTOR
- ☐ SERVO MOTOR
- ☐ STEPPER MOTOR
- ☐ GYROSCOPE
- ☐ ACCELEROMETER

- ☐ LIDAR
- ☐ ENCODER
- ☐ MICROCONTROLLER
- ☐ PID CONTROLLER
- ☐ TORQUE
- ☐ PAYLOAD

- ☐ PATH PLANNING
- ☐ ODOMETRY
- ☐ FEEDBACK LOOP
- ☐ TRAJECTORY
- ☐ HAPTIC
- ☐ MANIPULATOR

Robotics Engineering: answer key

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